

KHALIFA UNIVERSITY OF SCIENCE, TECHNOLOGY AND RESEARCH

MATH 204-LINEAR ALGEBRA- SPRING 2013

Home Work with Solutions 4- 24 March, 2013

Submissions Due on 1 April, 2013

1. Find a initial point P with terminal point $Q(3,0,-5)$ such that

a. $\vec{PQ}$ is equal to $\mathbf{v} = (4, -2, -1)$

b. $\vec{PQ}$ is equal to $\mathbf{v} = (4, -2, -1)$ with oppositely directed.

Sol)

a) Let $\mathbf{P} = (x, y, z)$ be the initial point of the desired vector.

$$\vec{PQ} = (3-x, 0-y, -5-z) = (4, -2, -1). \text{ Thus, } \mathbf{P} = (-1, 2, -4).$$

b) Let $\mathbf{P} = (x, y, z)$ be the initial point of the desired vector.

$$\vec{PQ} = (3-x, 0-y, -5-z) = -(4, -2, -1). \text{ Thus, } \mathbf{P} = (7, -2, -6).$$

2. Let $\mathbf{u} = (-3, 1, 2, 4, 4)$, $\mathbf{v} = (4, 0, -8, 1, 2)$, and $\mathbf{w} = (6, -1, -4, 3, -5)$. Find the components of the vector $\mathbf{x}$ that satisfies the equation $2\mathbf{u} + \mathbf{v} + \mathbf{x} = 6\mathbf{x} + \mathbf{w}$.

Sol) Let $\mathbf{x} = (x_1, x_2, x_3, x_4, x_5)$. Then

$$2(-3, 1, 2, 4, 4) + (4, 0, -8, 1, 2) + (x_1, x_2, x_3, x_4, x_5) = 6(x_1, x_2, x_3, x_4, x_5) + (6, -1, -4, 3, -5).$$

If we equate the components of these two vectors, we obtain

$$-2 + x_1 = 6x_1 + 6$$

$$2 + x_2 = 6x_2 - 1$$

$$-4 + x_3 = 6x_3 - 4$$

$$9 + x_4 = 6x_4 + 3$$

$$10 + x_5 = 6x_5 - 5$$

$$\text{Therefore, } \mathbf{x} = (x_1, x_2, x_3, x_4, x_5) = \left(-\frac{8}{5}, \frac{3}{5}, 0, \frac{6}{5}, 3\right).$$

3. Show that there do not exist scalars c_1, c_2, c_3 such that

$$c_1(-2, 9, 6) + c_2(-3, 2, 1) + c_3(1, 7, 5) = (0, 5, 4)$$

Sol) Suppose there are scalars c_1, c_2 , and c_3 which satisfy the given equation. If we equate components on both sides, we obtain the following system of equations:

$$\begin{aligned} -2c_1 - 3c_2 + c_3 &= 0 \\ 9c_1 + 2c_2 + 7c_3 &= 5 \\ 6c_1 + c_2 + 5c_3 &= 4 \end{aligned}$$

The augmented matrix of this system of equations can be reduced to

$$\left[\begin{array}{ccc|c} 2 & 3 & -1 & 0 \\ 9 & 2 & 7 & 5 \\ 6 & 1 & 5 & 4 \end{array} \right] \xrightarrow{\substack{R_2 = -2R_1 + 3R_3 \\ R_3 = -3R_1 + R_3}} \left[\begin{array}{ccc|c} 2 & 3 & -1 & 0 \\ 0 & -1 & 1 & 2 \\ 0 & -8 & 8 & 4 \end{array} \right] \xrightarrow{\substack{R_2 = -R_2 \\ R_3 = -8R_2 + R_3}} \left[\begin{array}{ccc|c} 2 & 3 & -1 & 0 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & -12 \end{array} \right]$$

The third row of the above matrix implies that $0c_1 + 0c_2 + 0c_3 = -12$. Clearly, there do not exist scalars c_1, c_2 , and c_3 which satisfy the above equation, and hence the system is inconsistent.

4. Let $\mathbf{v} = (0, 2, -6, 3)$. Find all scalars k such that $\|\mathbf{kv}\| = 14$.

Sol) Since $\mathbf{kv} = (0, 2k, -6k, 3k)$, then $\|\mathbf{kv}\| = \sqrt{4k^2 + 36k^2 + 9k^2} = \sqrt{49k^2} = |k|7$.

If $\|\mathbf{kv}\| = 14$, it follows that $7|k| = 14$, so $k=2$ and -2 .

5. Find a unit vector that has the same direction as the given vector.

a. $\mathbf{u} = (3, -4)$

b. $\mathbf{v} = (3, 6, -2)$

Sol) a) Since $\|\mathbf{u}\| = \sqrt{9+16} = 5$, then $\frac{1}{\|\mathbf{u}\|}\mathbf{u} = \left(\frac{3}{5}, -\frac{4}{5}\right)$.

b) Since $\|\mathbf{v}\| = \sqrt{9+36+4} = 7$, then $\frac{1}{\|\mathbf{v}\|}\mathbf{v} = \left(\frac{3}{7}, \frac{6}{7}, -\frac{2}{7}\right)$

6. Let $\mathbf{p}_0 = (x_0, y_0, z_0)$ and $\mathbf{p} = (x, y, z)$. Describe the set of all points (x, y, z) for which $\|\mathbf{p} - \mathbf{p}_0\| = 1$.

Sol) Note that $\|\mathbf{p} - \mathbf{p}_0\| = 1$ if and only if $\|\mathbf{p} - \mathbf{p}_0\|^2 = 1$. Thus

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = 1$$

The points (x, y, z) which satisfy these equations are just the points on the sphere of radius 1 with center (x_0, y_0, z_0) ; that is, they are all the points whose distance from (x_0, y_0, z_0) is 1.

7. Let $\mathbf{u} = (2, -1, 3)$ and $\mathbf{v} = (4, -1, 2)$. Find the vector component of $\mathbf{u}$ along $\mathbf{v}$ and the vector component of $\mathbf{u}$ orthogonal to $\mathbf{v}$.

Sol) The vector component of $\mathbf{u}$ along $\mathbf{v}$ is

$$\text{proj}_{\mathbf{v}} \mathbf{u} = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \mathbf{v} = \frac{2 \cdot 4 + (-1) \cdot (-1) + 3 \cdot 2}{4^2 + (-1)^2 + 2^2} \mathbf{v} = \frac{15}{21} (4, -1, 2) = \left(\frac{20}{7}, -\frac{5}{7}, \frac{10}{7} \right).$$

The vector component of $\mathbf{u}$ orthogonal to $\mathbf{v}$

$$\mathbf{u} - \text{proj}_{\mathbf{v}} \mathbf{u} = \mathbf{u} - \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \mathbf{v} = (2, -1, 3) - \left(\frac{20}{7}, -\frac{5}{7}, \frac{10}{7} \right) = \left(-\frac{6}{7}, -\frac{2}{7}, \frac{11}{7} \right).$$

8. Determine whether the vectors form an orthogonal set.

- a) $\mathbf{v}_1 = (1, 2)$, $\mathbf{v}_2 = (-2, 1)$
- b) $\mathbf{v}_1 = (2, 4)$, $\mathbf{v}_2 = (-1, 2)$
- c) $\mathbf{v}_1 = (1, 3, -1)$, $\mathbf{v}_2 = (-2, 2, 4)$, $\mathbf{v}_3 = (14, -2, 8)$
- d) $\mathbf{v}_1 = (5, -1, 2)$, $\mathbf{v}_2 = (-1, 2, 3)$, $\mathbf{v}_3 = (4, -1, 2)$

Sol)

- a. $\mathbf{v}_1 \cdot \mathbf{v}_2 = (1 \cdot -2) + (1 \cdot 2) = 0$, Orthogonal set
- b. $\mathbf{v}_1 \cdot \mathbf{v}_2 = (2 \cdot -1) + (4 \cdot 2) = 8$, Not orthogonal set

c. $\mathbf{v}_1 \cdot \mathbf{v}_2 = (1 \cdot -2) + (3 \cdot 2) + (1 \cdot 4) = 0$, $\mathbf{v}_1 \cdot \mathbf{v}_3 = (1 \cdot 14) + (3 \cdot -2) + (-1 \cdot 8) = 0$,

$\mathbf{v}_2 \cdot \mathbf{v}_3 = (-2 \cdot 14) + (2 \cdot -2) + (4 \cdot 8) = 0$, Orthogonal set

d. $\mathbf{v}_1 \cdot \mathbf{v}_2 = (5 \cdot -1) + (-1 \cdot 2) + (2 \cdot 3) = -1$, $\mathbf{v}_1 \cdot \mathbf{v}_3 = (5 \cdot 4) + (-1 \cdot -1) + (2 \cdot 2) = 25$,

$\mathbf{v}_2 \cdot \mathbf{v}_3 = (-1 \cdot 4) + (2 \cdot -1) + (3 \cdot 2) = 0$, Not orthogonal set

9. Show that if $\mathbf{v}$ is orthogonal to both $\mathbf{w}_1$ and $\mathbf{w}_2$, then $\mathbf{v}$ is orthogonal to $k_1\mathbf{w}_1 + k_2\mathbf{w}_2$ for all scalars k_1 and k_2 .

Sol) Note that $\mathbf{v} \cdot (k_1\mathbf{w}_1 + k_2\mathbf{w}_2) = k_1(\mathbf{v} \cdot \mathbf{w}_1) + k_2(\mathbf{v} \cdot \mathbf{w}_2) = 0$ because, by hypothesis, $\mathbf{v} \cdot \mathbf{w}_1 = \mathbf{v} \cdot \mathbf{w}_2 = 0$. Therefore $\mathbf{v}$ is orthogonal to $k_1\mathbf{w}_1 + k_2\mathbf{w}_2$ for any scalars k_1 and k_2 .

10. Let $\mathbf{u} = (3, 2, -1)$, $\mathbf{v} = (0, 2, -3)$, and $\mathbf{w} = (2, 6, 7)$. Compute the indicated vectors

a) $\mathbf{v} \times \mathbf{w}$

b) $(\mathbf{u} \times \mathbf{v}) \times \mathbf{w}$

c) $\mathbf{u} \times (\mathbf{v} - 2\mathbf{w})$

Sol) a. $\mathbf{v} \times \mathbf{w} = \left(\begin{vmatrix} 2 & -3 \\ 6 & 7 \end{vmatrix}, -\begin{vmatrix} 0 & -3 \\ 2 & 7 \end{vmatrix}, \begin{vmatrix} 0 & 2 \\ 2 & 6 \end{vmatrix} \right) = (32, -6, -4)$

b. Since $(\mathbf{u} \times \mathbf{v}) = \left(\begin{vmatrix} 2 & -1 \\ 2 & -3 \end{vmatrix}, -\begin{vmatrix} 3 & -1 \\ 0 & -3 \end{vmatrix}, \begin{vmatrix} 3 & 2 \\ 0 & 2 \end{vmatrix} \right) = (-4, 9, 6)$. We have

$$(\mathbf{u} \times \mathbf{v}) \times \mathbf{w} = \left(\begin{vmatrix} 9 & 6 \\ 6 & 7 \end{vmatrix}, -\begin{vmatrix} -4 & 6 \\ 2 & 7 \end{vmatrix}, \begin{vmatrix} -4 & 9 \\ 2 & 6 \end{vmatrix} \right) = (27, 40, -42).$$

c. Since $(\mathbf{u} - 2\mathbf{w}) = (0, 2, -3) - (4, 12, 14) = (-4, -10, -17)$. We have

$$\mathbf{u} \times (\mathbf{v} - 2\mathbf{w}) = \left(\begin{vmatrix} 2 & -1 \\ -10 & -17 \end{vmatrix}, -\begin{vmatrix} 3 & -1 \\ -4 & -17 \end{vmatrix}, \begin{vmatrix} 3 & 2 \\ -4 & -10 \end{vmatrix} \right) = (-44, -10, -17).$$

11. Determine whether the given set of vectors is linearly independent or linearly dependent.

a. $v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

b. $u_1 = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$, $u_2 = \begin{bmatrix} 4 \\ 4 \\ 0 \end{bmatrix}$, and $u_3 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$

Sol) a. $\begin{bmatrix} 1 & 2 & | & 0 \\ 2 & 3 & | & 0 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 - 2R_1} \begin{bmatrix} 1 & 2 & | & 0 \\ 0 & -1 & | & 0 \end{bmatrix} \xrightarrow{R_1 \rightarrow R_1 + 2R_2} \begin{bmatrix} 1 & 0 & | & 0 \\ 0 & -1 & | & 0 \end{bmatrix} \xrightarrow{R_2 \rightarrow -R_2} \begin{bmatrix} 1 & 0 & | & 0 \\ 0 & 1 & | & 0 \end{bmatrix}$, Only trivial solution, thus $\{v_1, v_2\}$ is linearly independent.

b.

$$\begin{pmatrix} 2 & 4 & 1 & | & 0 \\ 1 & 4 & 1 & | & 0 \\ -3 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & 4 & 1 & | & 0 \\ 2 & 4 & 1 & | & 0 \\ -3 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 + 3R_1}} \begin{pmatrix} 1 & 4 & 1 & | & 0 \\ 0 & -4 & -1 & | & 0 \\ 0 & 12 & 3 & | & 0 \end{pmatrix} \xrightarrow{R_2 \rightarrow -\frac{1}{4}R_2} \begin{pmatrix} 1 & 4 & 1 & | & 0 \\ 0 & 1 & 1/4 & | & 0 \\ 0 & 12 & 3 & | & 0 \end{pmatrix} \xrightarrow{\substack{R_1 \rightarrow R_1 - 4R_2 \\ R_3 \rightarrow R_3 - 12R_2}} \begin{pmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & 1/4 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$

Thus, $\{u_1, u_2, u_3\}$ is linearly dependent since there are solutions in addition to the trivial solution. For example, $x_1 = 0, x_2 = -\frac{1}{4}, x_3 = 1$.

12. Determine which of the following are subspaces of $\mathbb{R}^3$.

- a. All vectors of the form $(a, 0, 0)$
- b. All vectors of the form $(a, 1, 1)$
- c. All vectors of the form $(a, b, 0)$

Sol).

a) The set is closed under vector addition because $(a, 0, 0) + (b, 0, 0) = (a + b, 0, 0)$.

It is closed under scalar multiplication because $k(a, 0, 0) = (ka, 0, 0)$. Therefore, it is a subspace of $\mathbb{R}^3$.

b) This set is not closed under either vector addition or scalar multiplication.

For example, $(a, 1, 1) + (b, 1, 1) = (a + b, 2, 2)$ and $(a + b, 2, 2)$ does not belong to the set. Thus it is not a subspace.

c) This set is closed under vector addition because $(a_1, b_1, 0) + (a_2, b_2, 0) = (a_1 + a_2, b_1 + b_2, 0)$. It is also closed under scalar multiplication because $k(a, b, 0) = (ka, kb, 0)$.

Therefore, it is a subspace of $\mathbb{R}^3$.

13. Let **A** and **B** be 4x5 matrices and let **C**, **D** and **E** be 5x2, 4x2 and 5x4 matrices, respectively. Determine which of the following matrix expressions are defined. For those that are defined, give the size of the resulting matrix.

- BA, AC+D, AE+B**
- AB+B, E(A+B), E(AC)**

Sol)

a) $\mathbf{B}_{4 \times 5} \mathbf{A}_{4 \times 5}$: Because the number of column in B is not equal to the number of row in A, this matrix is not defined.

$\mathbf{A}_{4 \times 5} \mathbf{C}_{5 \times 2} + \mathbf{D}_{4 \times 2}$: 4x2 matrix is defined.

$\mathbf{A}_{4 \times 5} \mathbf{E}_{5 \times 4} + \mathbf{B}_{4 \times 5}$: The matrix is not defined.

b) $\mathbf{A}_{4 \times 5} \mathbf{B}_{4 \times 5} + \mathbf{B}_{4 \times 5}$: The matrix is not defined.

$\mathbf{E}_{5 \times 4} (\mathbf{A}_{4 \times 5} + \mathbf{B}_{4 \times 5})$: 5x5 matrix is defined.

$\mathbf{E}_{5 \times 4} (\mathbf{A}_{4 \times 5} \mathbf{C}_{5 \times 2})$: 5x2 matrix is defined.

14. Show that if **AB** and **BA** are both defined, then **AB** and **BA** are square matrices.

Sol) Let **A** and **B** define $m \times n$ and $p \times q$ matrices, respectively. If $\mathbf{A}_{m \times n} \mathbf{B}_{p \times q}$ is defined, it implies that $n=p$. Similarly, if $\mathbf{B}_{p \times q} \mathbf{A}_{m \times n}$ is defined, it implies that $q=m$. Thus, $\mathbf{A}_{m \times n} \mathbf{B}_{p \times q} = \mathbf{C}_{m \times q}$, which is square matrix (since $q=m$). As same way, $\mathbf{B}_{p \times q} \mathbf{A}_{m \times n} = \mathbf{D}_{p \times n}$, is square matrix (since $n=p$).

15. Solve the following equation $\begin{pmatrix} a-b & b+c \\ 3d+c & 2a-4d \end{pmatrix} - \begin{pmatrix} 8 & 1 \\ 7 & 6 \end{pmatrix} = \mathbf{0}$.

$$\text{Sol)} \begin{pmatrix} a-b & b+c \\ 3d+c & 2a-4d \end{pmatrix} - \begin{pmatrix} 8 & 1 \\ 7 & 6 \end{pmatrix} = \begin{pmatrix} a-b-8 & b+c-1 \\ 3d+c-7 & 2a-4d-6 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Thus, $a-b-8=0$, $b+c-1=0$, $3d+c-7=0$, and $2a-4d-6=0$

Therefore, $a=5$, $b=-3$, $c=4$, and $d=1$.

16. Express the following system of equations

$$2x_1 + 4x_2 - 2x_3 - 2 = 0$$

$$3x_1 + 5x_2 - 5x_3 = 1$$

$$2x_2 + x_3 = -2$$

in the matrix expression of the form $\mathbf{Ax} = \mathbf{b}$, where $\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$. Write down the matrices $\mathbf{A}$ and $\mathbf{b}$.

Sol) The matrix expression of the form $\mathbf{Ax} = \mathbf{b}$ is as follows;

$$\begin{pmatrix} 2 & 4 & -2 \\ 3 & 5 & -5 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix}.$$

Therefore, $\mathbf{A} = \begin{pmatrix} 2 & 4 & -2 \\ 3 & 5 & -5 \\ 0 & 2 & 1 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix}$.

17. Prove that $(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T$.

Sol) The ij th entry of $\mathbf{B}^T \mathbf{A}^T$ is the scalar product of the i th row of $\mathbf{B}^T$ with the j th column of $\mathbf{A}^T$. In particular, the i th row of $\mathbf{B}^T$ is $[b_{1i}, b_{2i}, \dots, b_{ni}]$ (the i th column of $\mathbf{B}$), whereas the j th

column of $\mathbf{A}^T$ is $\begin{pmatrix} a_{j1} \\ a_{j2} \\ \vdots \\ a_{jn} \end{pmatrix}$ (the j th row of $\mathbf{A}$). Therefore, the ij th entry of $\mathbf{B}^T \mathbf{A}^T$ is given by

$b_{1i}a_{j1} + b_{2i}a_{j2} + \dots + b_{ni}a_{jn} = \sum_{k=1}^n b_{ki}a_{jk}$. Finally, since $\sum_{k=1}^n b_{ki}a_{jk} = \sum_{k=1}^n a_{jk}b_{ki}$, the ij th entries of $(\mathbf{AB})^T$ and $\mathbf{B}^T \mathbf{A}^T$ agree, and the matrices are equal.

18. Let $\mathbf{A}$ and $\mathbf{B}$ 2×2 matrices such that $\mathbf{A}^2 = \mathbf{AB}$ and $\mathbf{A} \neq \mathbf{0}$. A student proof that if $\mathbf{A}^2 = \mathbf{AB}$ then $\mathbf{A} = \mathbf{B}$. The proof is given below: Since $\mathbf{A}^2 = \mathbf{AB}$, $\mathbf{A}^2 - \mathbf{AB} = \mathbf{0}$ which implies $\mathbf{A}(\mathbf{A} - \mathbf{B}) = \mathbf{0}$. Since $\mathbf{A} \neq \mathbf{0}$, it follows that $(\mathbf{A} - \mathbf{B}) = \mathbf{0}$. Therefore, $\mathbf{A} = \mathbf{B}$. Is this proof correct?

Sol) No. When $\mathbf{A}(\mathbf{A} - \mathbf{B}) = \mathbf{0}$ with $\mathbf{A} \neq \mathbf{0}$, it does not always imply that $(\mathbf{A} - \mathbf{B}) = \mathbf{0}$. For example, $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$.

19. Let $\mathbf{a} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$, Find $\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$ such that $\mathbf{x}^T (\mathbf{a} + \mathbf{b}) = 12$ and $\mathbf{x}^T \mathbf{a} = 2$.

$$\text{Sol) } \mathbf{x}^T (\mathbf{a} + \mathbf{b}) = (x_1 \ x_2) \left(\begin{pmatrix} 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 3 \\ 4 \end{pmatrix} \right) = 12, \quad \mathbf{x}^T \mathbf{a} = (x_1 \ x_2) \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 2$$

Thus, $4x_1 + 6x_2 = 12$ and $x_1 + 2x_2 = 2$. Therefore, $x_1 = 6$, $x_2 = -2$

20. Let $\mathbf{A} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ and $\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$. Show that $\mathbf{x}^T \mathbf{A} \mathbf{x} \geq 0$.

$$\text{Sol) } \mathbf{x}^T \mathbf{A} \mathbf{x} = [x_1 \ x_2] \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = (x_1 + x_2 \ x_1 + x_2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = [x_1(x_1 + x_2) + x_2(x_1 + x_2)]$$

Therefore, $[x_1(x_1 + x_2) + x_2(x_1 + x_2)] = x_1^2 + 2x_1x_2 + x_2^2 = (x_1 + x_2)^2 \geq 0$.

21. Let $\mathbf{A}$ be an invertible matrix whose inverse is $\begin{pmatrix} 3 & 4 \\ 5 & 6 \end{pmatrix}$. Find the matrix $\mathbf{A}$.

Sol) Let $\mathbf{A}$ define $\mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. Since $\mathbf{A}$ is an invertible matrix, $\mathbf{A} \mathbf{A}^{-1} = \mathbf{I}$. Thus,

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 3 & 4 \\ 5 & 6 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 3a+5b & 4a+6b \\ 3c+5d & 4c+6d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Therefore, $a=-3$, $b=2$, $c=5/2$, and $d=-3/2$.

22. Find the inverse of $\begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$.

Sol) Let $\mathbf{A} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$. $\mathbf{A}^{-1} = \frac{1}{\cos^2 \theta + \sin^2 \theta} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

23. Assume that $\mathbf{A}$ is a square matrix and which satisfies $\mathbf{A}^2 - 3\mathbf{A} + \mathbf{I} = \mathbf{0}$. Show that $\mathbf{A}^{-1} = 3\mathbf{I} - \mathbf{A}$.

Sol) $\mathbf{A}^2 - 3\mathbf{A} + \mathbf{I} = \mathbf{0} \rightarrow \mathbf{A}^{-1}\mathbf{A}\mathbf{A} - 3\mathbf{A}^{-1}\mathbf{A} + \mathbf{A}^{-1}\mathbf{I} = \mathbf{A}^{-1}\mathbf{0}$ Multiply $\mathbf{A}^{-1}$ to each term.

$\mathbf{I}\mathbf{A} - 3\mathbf{I} + \mathbf{A}^{-1} = \mathbf{0}$. Therefore, $\mathbf{A}^{-1} = 3\mathbf{I} - \mathbf{A}$.

24. Prove that if $\mathbf{A}$ is invertible and $\mathbf{AB} = \mathbf{0}$, then $\mathbf{B} = \mathbf{0}$.

Sol) Since $\mathbf{A}$ is invertible, it is possible that $\mathbf{A}^{-1}\mathbf{AB} = \mathbf{A}^{-1}\mathbf{0} \Rightarrow \mathbf{IB} = \mathbf{0} \Rightarrow \mathbf{B} = \mathbf{0}$.

25. Let $\mathbf{A}$ is square matrix and assume $\mathbf{A}^3 = 3\mathbf{A}^2 - 3\mathbf{A} + \mathbf{I}$. Express $\mathbf{A}^4$ in terms of $\mathbf{A}^2$, $\mathbf{A}$, and $\mathbf{I}$.

Sol) $\mathbf{A}^4 = \mathbf{A}^3\mathbf{A} = (3\mathbf{A}^2 - 3\mathbf{A} + \mathbf{I})\mathbf{A} = 3\mathbf{A}^3 - 3\mathbf{A}^2 + \mathbf{A} = 3(3\mathbf{A}^2 - 3\mathbf{A} + \mathbf{I}) - 3\mathbf{A}^2 + \mathbf{A}$
 $= 3(3\mathbf{A}^2 - 3\mathbf{A} + \mathbf{I}) - 3\mathbf{A}^2 + \mathbf{A} = 6\mathbf{A}^2 - 8\mathbf{A} + 3\mathbf{I}$.

26. Show that the given matrix is not invertible. $\mathbf{A} = \begin{pmatrix} 1 & 6 & 4 \\ 2 & 4 & -1 \\ -1 & 2 & 5 \end{pmatrix}$

Sol) Using row operations to find $\mathbf{A}^{-1}$,

$$\left(\begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 2 & 4 & -1 & 0 & 1 & 0 \\ -1 & 2 & 5 & 0 & 0 & 1 \end{array} \right)$$

$$\left(\begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 2 & -8 & -9 & -2 & 1 & 0 \\ 0 & 8 & 9 & 1 & 0 & 1 \end{array} \right) \text{ Added -2 times the first row to the second and added the first row to the third.}$$

$$\left(\begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 & 1 \end{array} \right) : \text{Added the second row to the third.}$$

Since we have obtained a row of zeros on the left side, $\mathbf{A}$ is not invertible.

27. Evaluate the determinants (a) $\det(\mathbf{A}) = \begin{vmatrix} 3 & 1 & 0 \\ -2 & -4 & 3 \\ 5 & 4 & -2 \end{vmatrix}$, (b) $\det(\mathbf{B}) = \begin{vmatrix} 1 & 0 & 0 & -1 \\ 3 & 1 & 2 & 2 \\ 1 & 0 & -2 & 1 \\ 2 & 0 & 0 & 1 \end{vmatrix}$.

Sol). (a) $\det(\mathbf{A}) = \begin{vmatrix} 3 & 1 & 0 \\ -2 & -4 & 3 \\ 5 & 4 & -2 \end{vmatrix} = 3 \begin{vmatrix} -4 & 3 \\ 4 & 2 \end{vmatrix} - 1 \begin{vmatrix} -2 & 3 \\ 5 & -2 \end{vmatrix} + 0 \begin{vmatrix} -2 & -4 \\ 5 & 4 \end{vmatrix} = 3(-4) - (1)(-11) + 0 = -1$

(b) To find $\det(\mathbf{B})$ it will be easiest to use cofactor expansion along the second column since it has the most zeros:

$$\det(\mathbf{B}) = \begin{vmatrix} 1 & 0 & 0 & -1 \\ 3 & 1 & 2 & 2 \\ 1 & 0 & -2 & 1 \\ 2 & 0 & 0 & 1 \end{vmatrix} = 1 \begin{vmatrix} 1 & 0 & -1 \\ 1 & -2 & 1 \\ 2 & 0 & 1 \end{vmatrix}$$

For the 3x3 determinant, it will be easiest to use cofactor expansion along its second column since it has the most zeros:

$$\det(\mathbf{B}) = 1 \cdot -2 \begin{vmatrix} 1 & -1 \\ 2 & 1 \end{vmatrix} = -2(1+2) = -6.$$

28. For which value(s) of k does the matrix $\begin{pmatrix} k-3 & -2 \\ -2 & k-2 \end{pmatrix}$ fail to be invertible?

Sol) Since the given matrix fail to be invertible, it implies that its determinant is zero.

$$\det(\mathbf{A}) = (k-3)(k-2) - 4 = 0, \quad k^2 - 5k + 2 = 0. \text{ Therefore, } k = \frac{5 \pm \sqrt{25-8}}{2} = \frac{5 \pm \sqrt{17}}{2}.$$

29. Assume that $\mathbf{A}$ is 4×4 matrix and $\det(\mathbf{A})=4$. Find

(a) $\det(3\mathbf{A})$ (b) $\det(2\mathbf{A}^{-1})$ (c) $\det((2\mathbf{A})^{-1})$.

Sol)

a) By basic properties of determinants ($\det(k\mathbf{A}) = k^n \det(\mathbf{A})$), $\det(3\mathbf{A}) = 3^4 \det(\mathbf{A}) = 324$.

b) By basic properties of determinants ($\det(\mathbf{A}^{-1}) = \frac{1}{\det(\mathbf{A})}$),

$$\det(2\mathbf{A}^{-1}) = 2^4 \det(\mathbf{A}^{-1}) = 16 * \frac{1}{\det(\mathbf{A})} = 4.$$

$$\text{c) } \det((2\mathbf{A})^{-1}) = \frac{1}{\det((2\mathbf{A}))} = \frac{1}{2^4 * \det(\mathbf{A})} = \frac{1}{64}.$$